

Specification Parameters

40S Parallel Two-Finger Gripper Model : CTPM2F40S



Model	CTPM2F40S	Maximum Stroke	40 mm
Drive Method	Motor-driven	Maximum Current	1.2 A
Maximum Gripping Force	60-300 N	Working Voltage	24 V
Maximum Gripping Speed	20 mm/s	Self-weight	1.1 kg
Repetitive Positioning Accuracy ±0.02 mm			
Feedbackable Parameters	Position, Speed, Force		
Recommended Operating Environment 0~40 ° C, below 85%RH (without condensation)			
Communication Protocol	Modbus RTU+IO (extensible to CAN, TCP/IP, EtherCAT, Profinet, etc.)		

Integrated Drive & Control, Precision Control, Lightweight Design, Long Service Life

Note: Gripper fingers are not included

Product dimensions diagram

