

Specification Parameters

60S Parallel Two-Finger Gripper Model : CTPM2F60S



Model	CTPM2F60S	Maximum Stroke	60 mm
Drive Method	Motor-driven	Maximum Gripping Speed	30 mm/s
Maximum Gripping Force	350-700N	Maximum Current	2 A
Repetitive Positioning Accuracy	±0.02 mm	Self-weight	2.1 kg
Working Voltage	24 V		
Feedbackable Parameters	Position, Speed, Force		
Recommended Operating Environment	0~40 ° C, below 85%RH (without condensation)		
Communication Protocol	Modbus RTU+IO (extensible to CAN, TCP/IP, EtherCAT, Profinet, etc.)		

Integrated Drive & Control, Precision Control, Lightweight Design, Long Service Life

Note: Gripper fingers are not included

Product dimensions diagram

